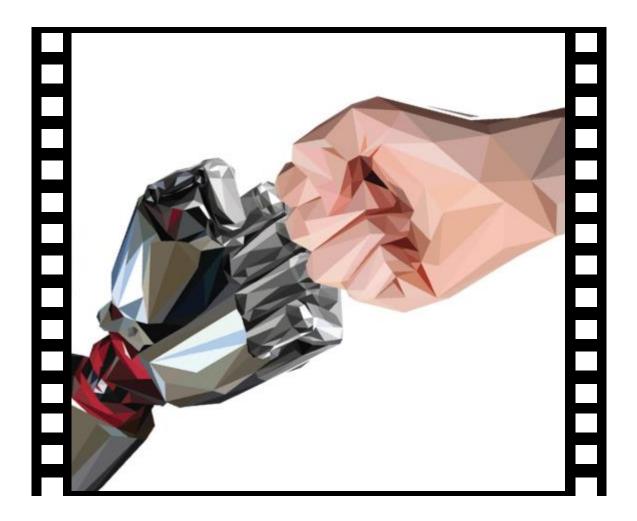


Industrial Cobotics for the factory of the future

David Bitonneau & Théo Moulières-Seban 30/03/2017



COBOTICS \neq ROBOTICS



WHY COBOTICS ?

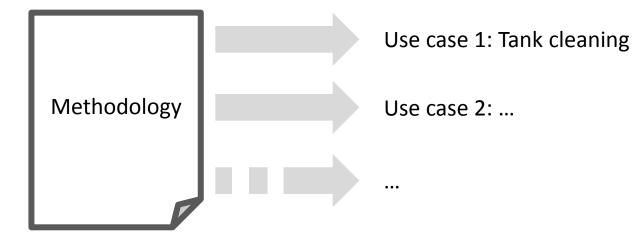


INTRODUCTION

Pluridisciplinary team

- Ergonomics
- Cognitics
- Robotics

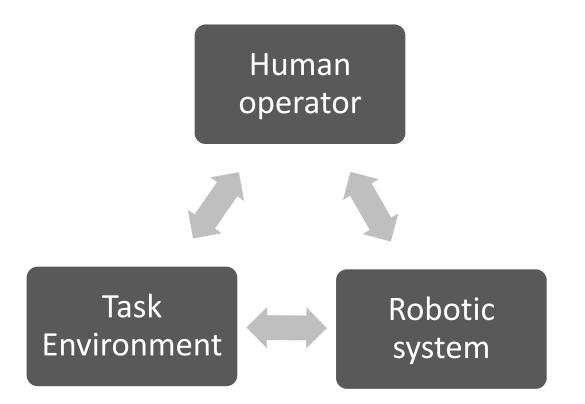






« Cobotization » methodology

Goal: help to design cobotic systems

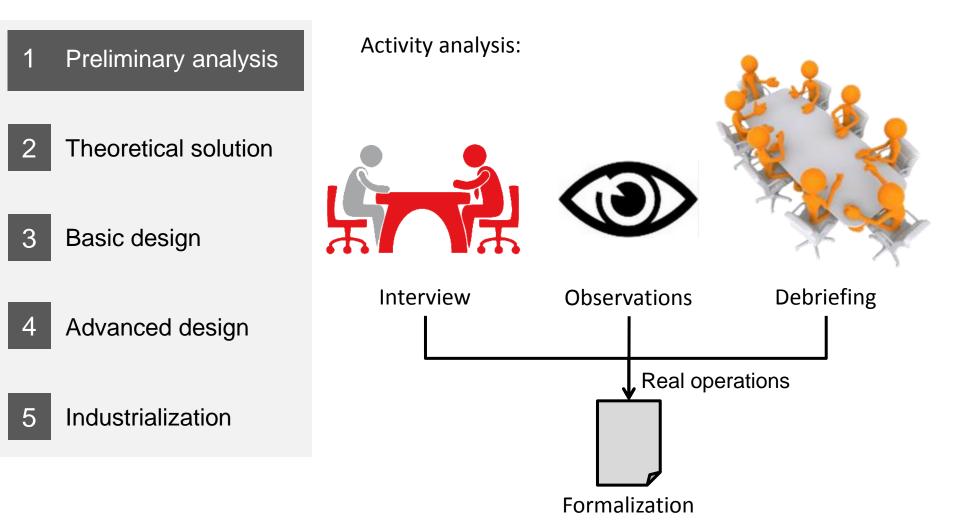


Moulières-Seban T., Bitonneau D., Thibault JF., Salotti JM., Claverie B., « Human Factors Issues for the Design of a Cobotic System » AHFE 2016, Orlando, E.-U., juillet 2016



- Preliminary analysis
- 2 Theoretical solution
- 3 Basic design
- 4 Advanced design
- 5 Industrialization





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- 2 Theoretical solution
- 3 Basic design
- 4 Advanced design
- 5 Industrialization

Technology review:



Moulières-Seban T., Bitonneau D., Thibault JF., Salotti JM., Claverie B., « Les Interactions Homme Robot pour la Cobotique Industrielle » ErgoIA 2016 Bidart, juillet 2016



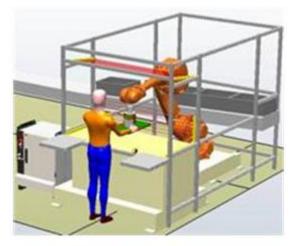
- 2 Theoretical solution
- 3 Basic design
- 4 Advanced design
- 5 Industrialization

Theoretical solution:











- 2 Theoretical solution
- 3 Basic design
- 4 Advanced design

5 Industrialization

Simulation-based approach with the future users:







- 2 Theoretical solution
- 3 Basic design
- 4 Advanced design

5 Industrialization

- Technical specifications
- Setting up
- Teaching
- Certification
- Putting into service



Use case: Tank cleaning

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Removed pictures for confidentiality reasons



Goals:

- Improve working conditions
- Remote pyrotechnic operations
- Reduce cycle time







Teleoperated scrubbing test:



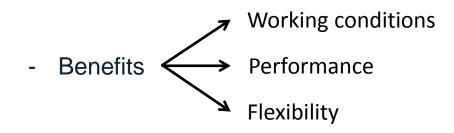
CONCLUSION

Methodology:

- Interdisciplinary team
- Including safety and normative aspects
- To be completed (industrialization step in progress)
- Currently tested through other projects

CONCLUSION

Cobotics:



Pyrotechnic workstations
Teleoperation

SPECIAL THANKS TO









